

The background of the slide is a checkerboard pattern. Each square of the checkerboard contains a different traffic sign, such as speed limits (30, 50, 60, 70, 80, 100, 120), directional arrows, and warning symbols. In the upper right quadrant, there is a circular inset showing a close-up of a red traffic light lens.

DEEP LEARNING REINFORCEMENT

JÜRGEN SCHMIDHUBER 2013

JÜRGEN SCHMIDHUBER, THE SWISS AI LAB IDSIA (USI & SUPSI)

JÜRGEN SCHMIDHUBER
YOU_AGAIN SHMIDHOObUH

deep learning overview

DEEP LEARNING IS A HALF CENTURY OLD
(RECENT “TABLOID SCIENCE” STORIES
CLAIM IT IS A RECENT THING)

888 references, 88 pages: <http://www.idsia.ch/~juergen/deep-learning-overview.html>

FIRST DEEP LEARNING: IVAKHNENKO, 1965 -

Deep multilayer perceptrons with
polynomial activation functions
incremental layer-wise training
by regression analysis - learn
numbers of layers and units per
layer - prune superfluous units
numerous applications
8 layers already back in 1971



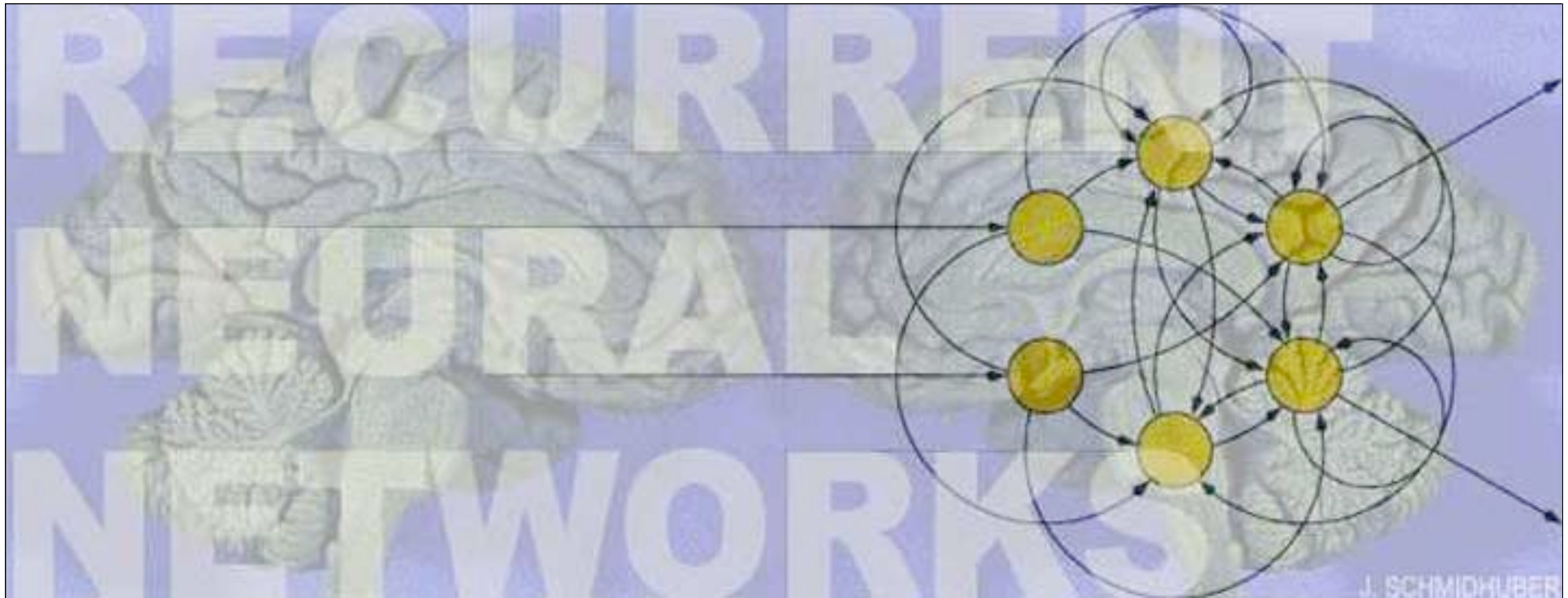
who
invented
backpropagation?

<http://www.idsia.ch/~juergen/who-invented-backpropagation.html>

SUPERVISED BACKPROPAGATION (BP)

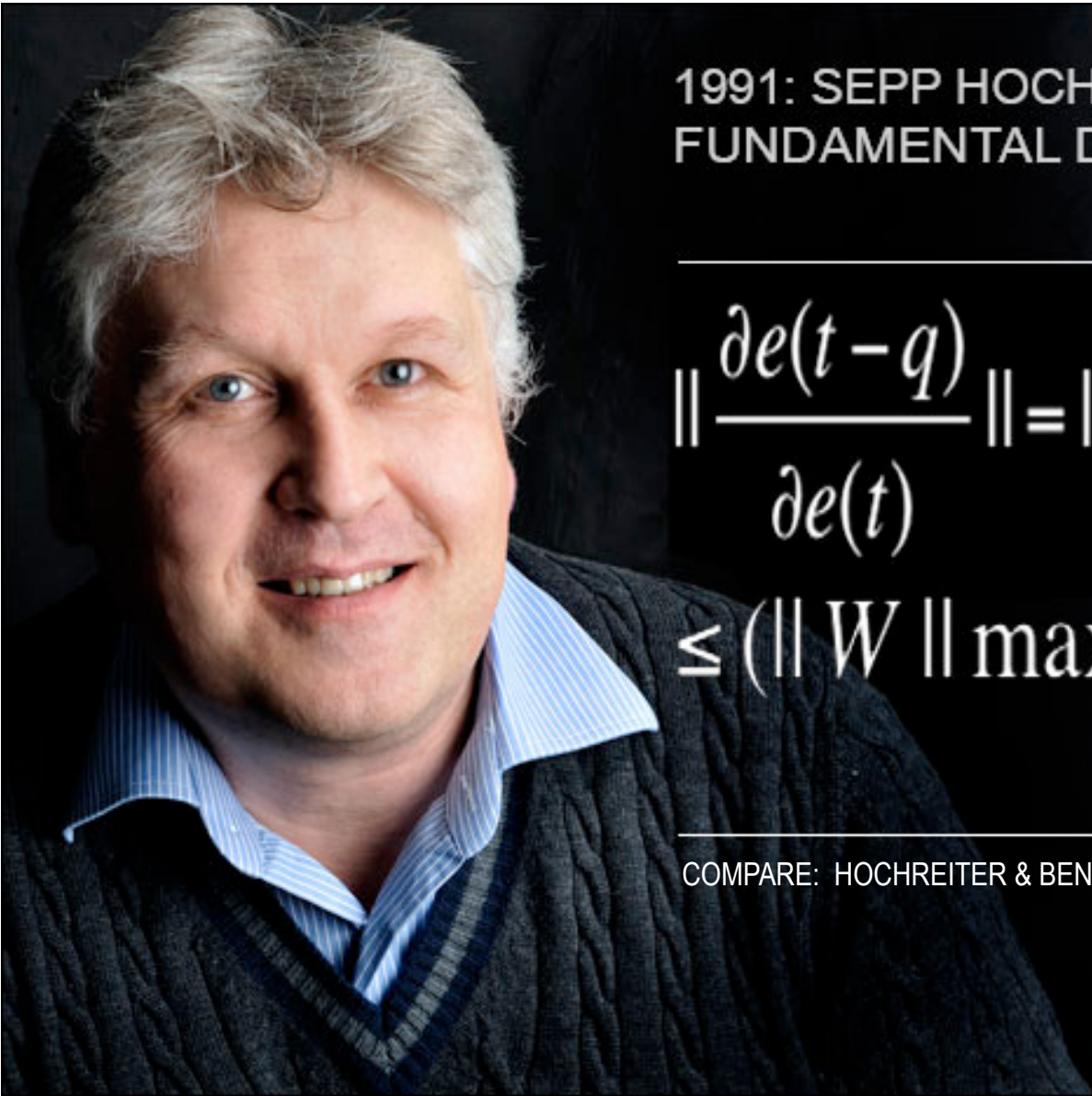
BP in Euler-LaGrange Calculus + Dynamic Programming: [Bryson 1961](#), [Kelley 60](#), [Dreyfus 62](#), Pontryagin et al 61, Bryson & Ho 69. BP in sparse, discrete, NN-like nets: [Linnainmaa 1970](#), Ostrovskii et al 71, Dreyfus 73, Werbos 74, Automatic Differentiation: [Speelpenning 80](#). BP for NNs: [Werbos 1981](#) (LeCun 85, Parker 85), Rumelhart et al 86; [RNNs](#): e.g., Werbos 88, Williams 89; Robinson & Fallside 87...





THE DEEPEST NNs:
RNNs ARE GENERAL COMPUTERS
LEARN PROGRAM = WEIGHT MATRIX

<http://www.idsia.ch/~juergen/rnn.html>

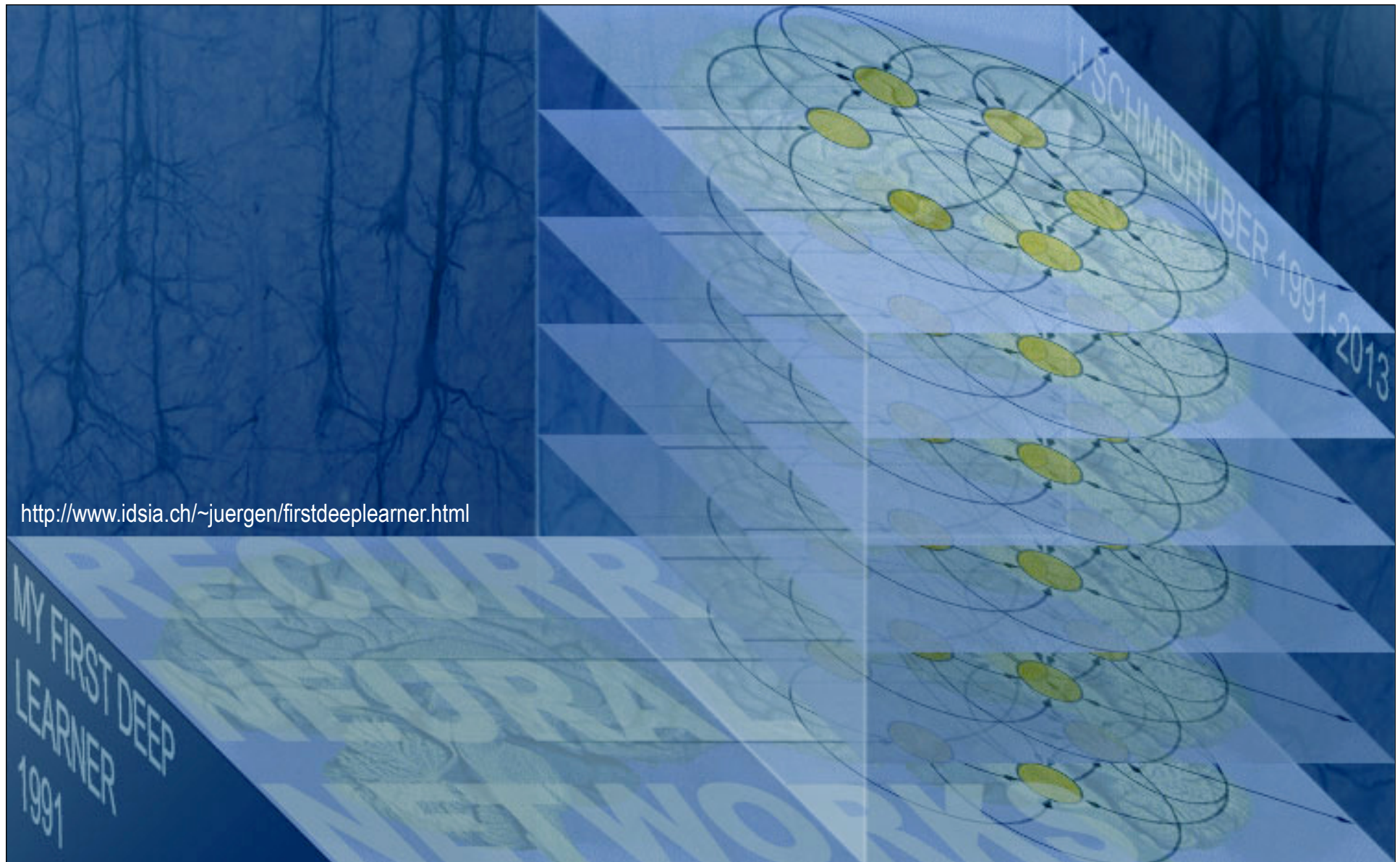


1991: SEPP HOCHREITER'S ANALYSIS OF THE
FUNDAMENTAL DEEP LEARNING PROBLEM

$$\left\| \frac{\partial e(t-q)}{\partial e(t)} \right\| = \left\| \prod_{m=1}^q W F'(Net(t-m)) \right\|$$
$$\leq (\|W\| \max_{Net} \{ \|F'(Net)\| \})^q$$

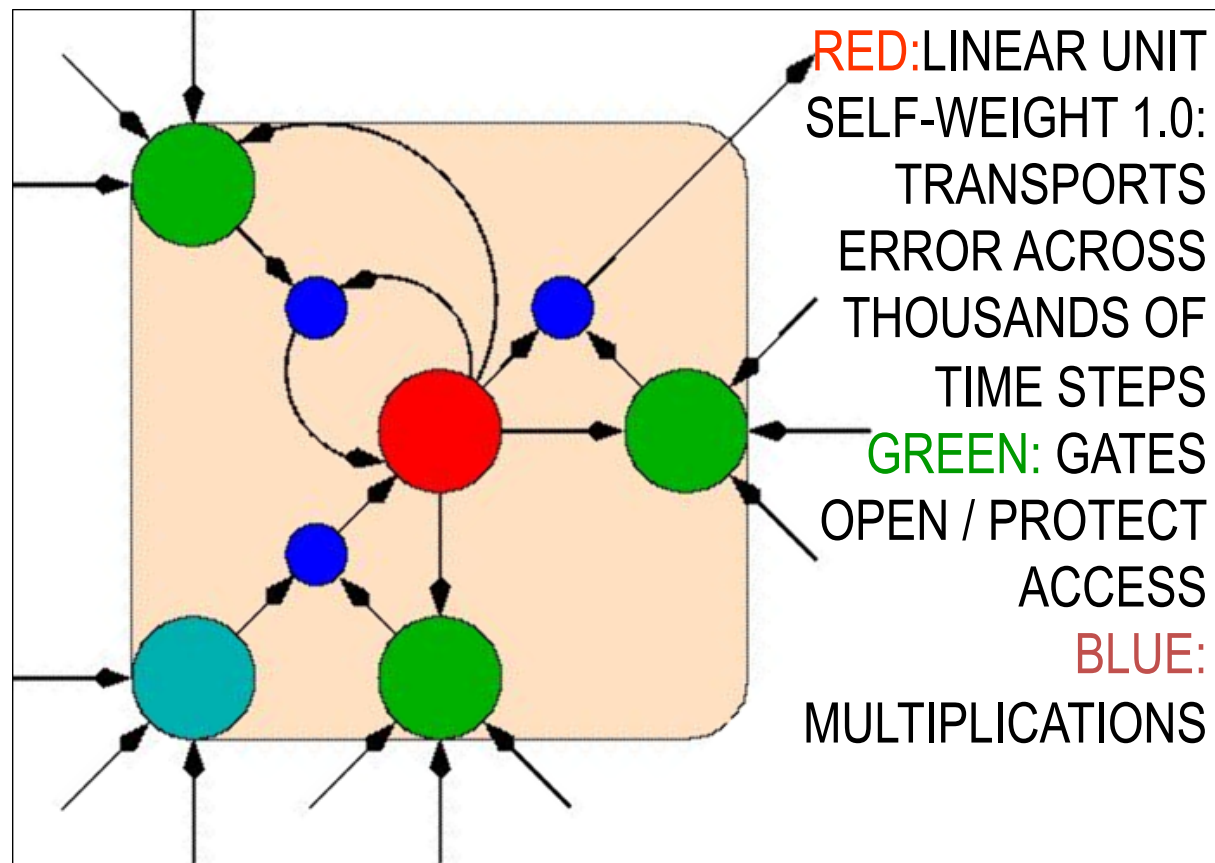
COMPARE: HOCHREITER & BENGIO & FRASCONI & SCHMIDHUBER, 2001

<http://www.idsia.ch/~juergen/fundamentaldeeplearningproblem.html>



<http://www.idsia.ch/~juergen/firstdeeplearner.html>

Schmidhuber 1991: Unsupervised pretraining for Hierarchical Temporal Memory: stack of RNN
→ history compression → speed up supervised learning. Compare feedforward NN case:
AutoEncoder stacks (Ballard 1987) and Deep Belief NNs (Hinton et al 2006)



RNN: LONG
 SHORT-
 TERM
 MEMORY
 LSTM: NO
 VANISHING
 GRADIENTS

GRADIENT-BASED LSTM (1995, Neural Comp. 1997) LEARNS MANY PREVIOUSLY UNLEARNABLE DEEP LEARNING TASKS: GRAMMARS, BLUES COMPOSITION, R-LEARNING ROBOTS, METALEARNING, SPEECH RECOGNITION (>HMMS), PROTEINS, HANDWRITING. NO BIAS TOWARDS RECENT OR ANCIENT EVENTS!

Today's LSTM RNNs shaped by:

Ex-PhD students (TUM & IDSIA):

Sepp Hochreiter (PhD 1999)

Felix Gers (PhD 2001)

Alex Graves (PhD 2008)

Daan Wierstra (PhD 2010)

Others

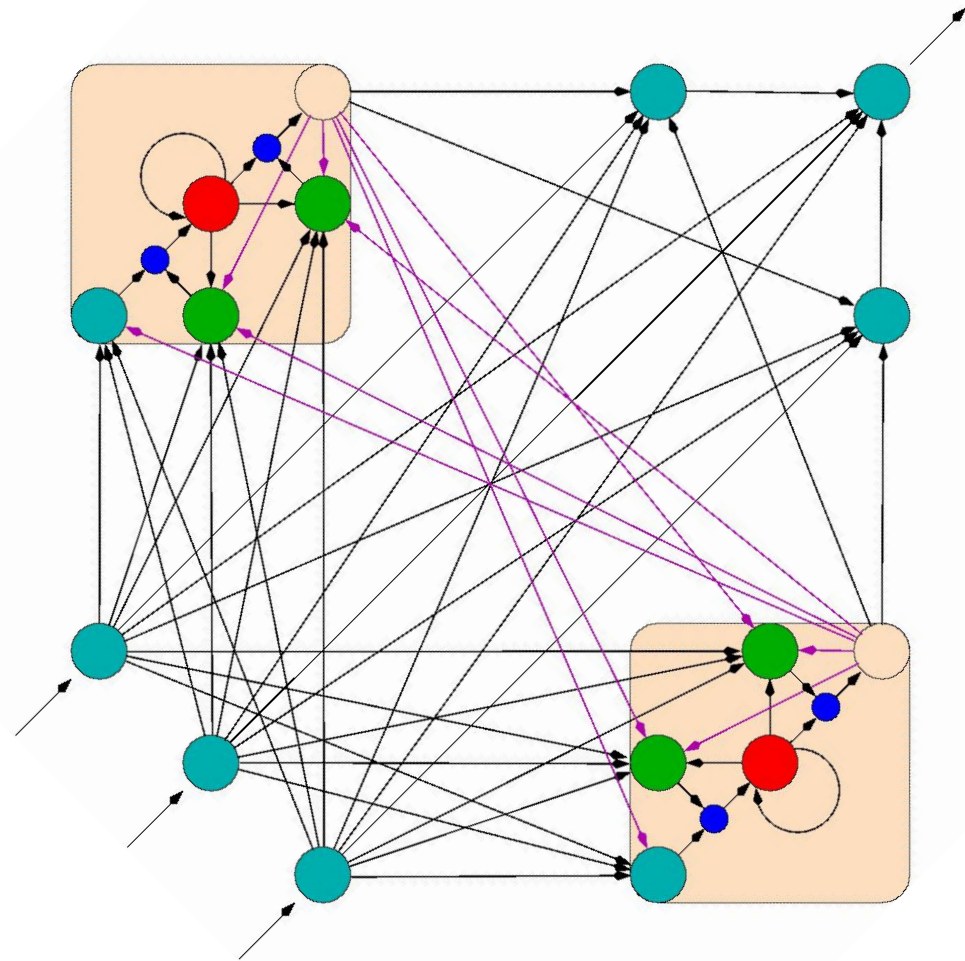
Postdocs at IDSIA (2000s):

Fred Cummins

Santiago Fernandez

Faustino Gomez

Others



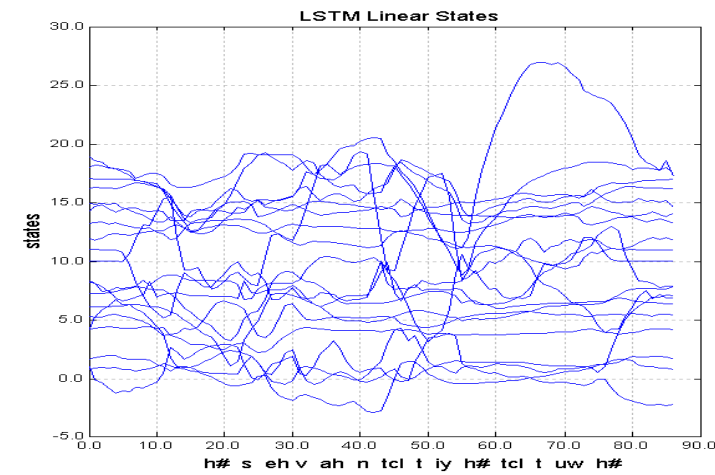
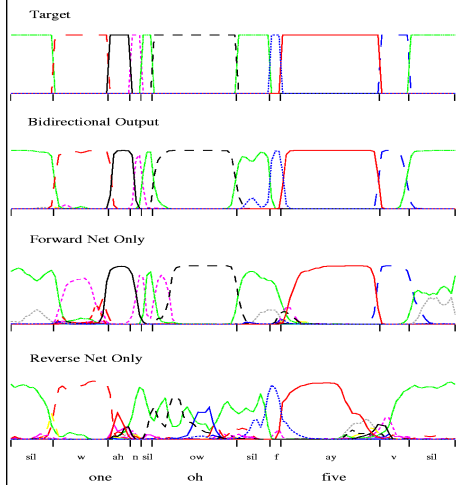
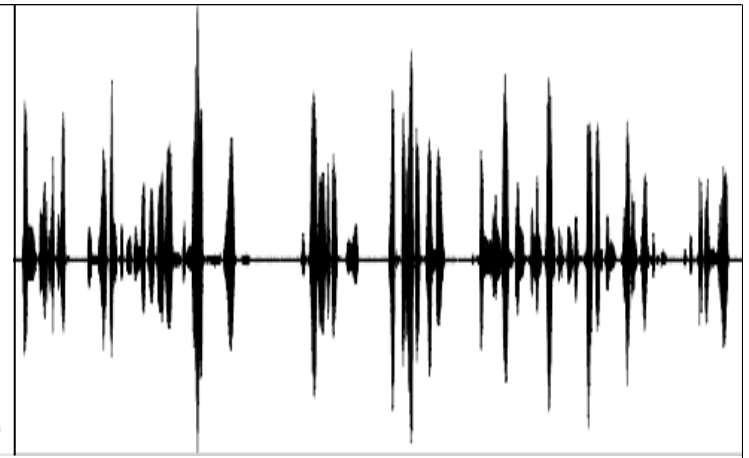
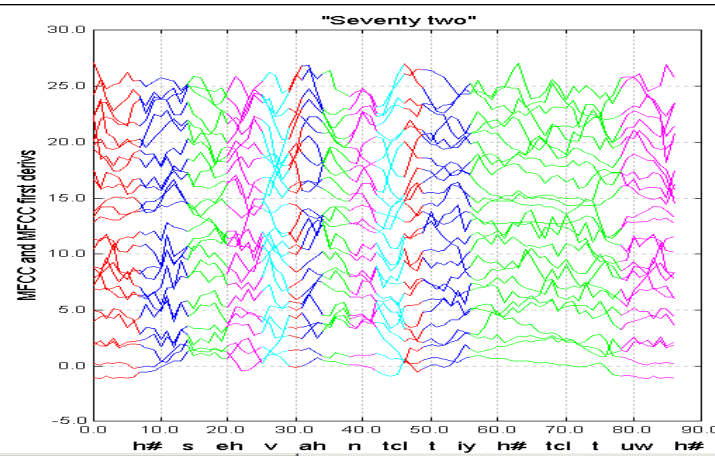


DEEP FEEDFORWARD NNs:
DAN CIRESAN,
UELI MEIER,
JONATHAN MASCI,
ALESSANDRO GIUSTI,
OTHERS

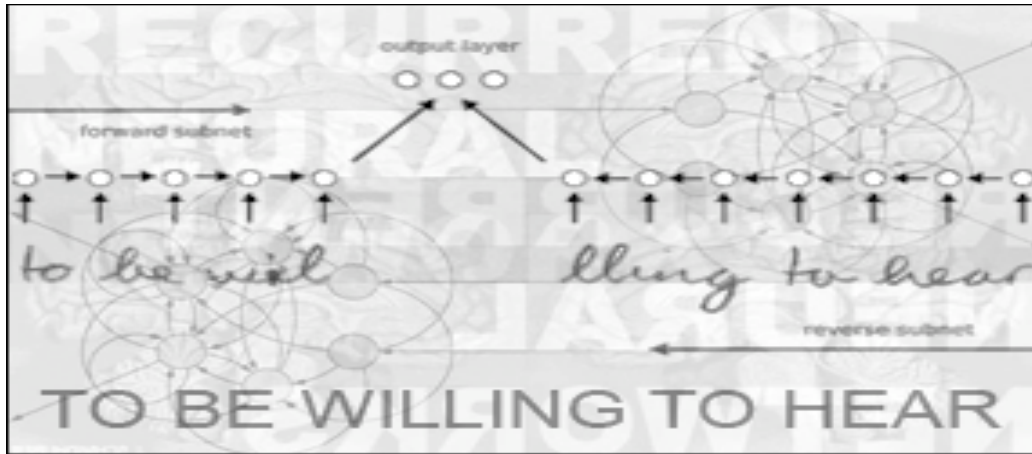
VERY DEEP LEARNING SINCE 1991
FUNDED BY DFG & SNF



SANTIAGO
FERNANDEZ

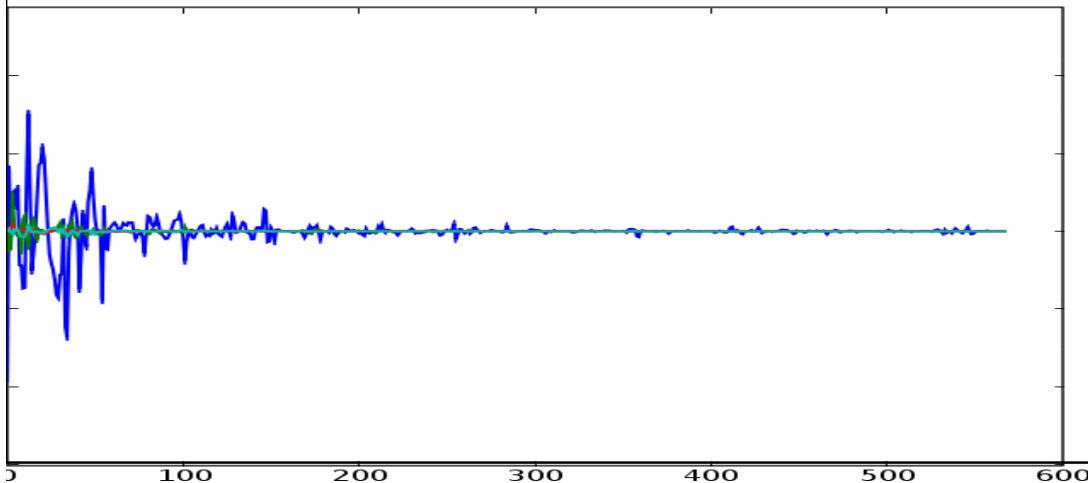


LSTM-RNN FOR SPEECH: 2003
COMPARABLE TO HMMS, IJCAI
2007: LSTM STACK GETS
BEST RESULTS ON KEYWORD
SPOTTING IN A LARGE
CORPUS (VS HMMS)



SUPERVISED LONG SHORT-TERM MEMORY (LSTM) RNN
 WON 3 ICDAR 2009
 CONNECTED
 HANDWRITING
 COMPETITIONS

<http://www.idsia.ch/~juergen/handwriting.html>



NO PRE-SEGMENTED
 DATA; RNN MAXIMISES
 PROBABILITY OF TRAINING
 SET LABEL SEQUENCES

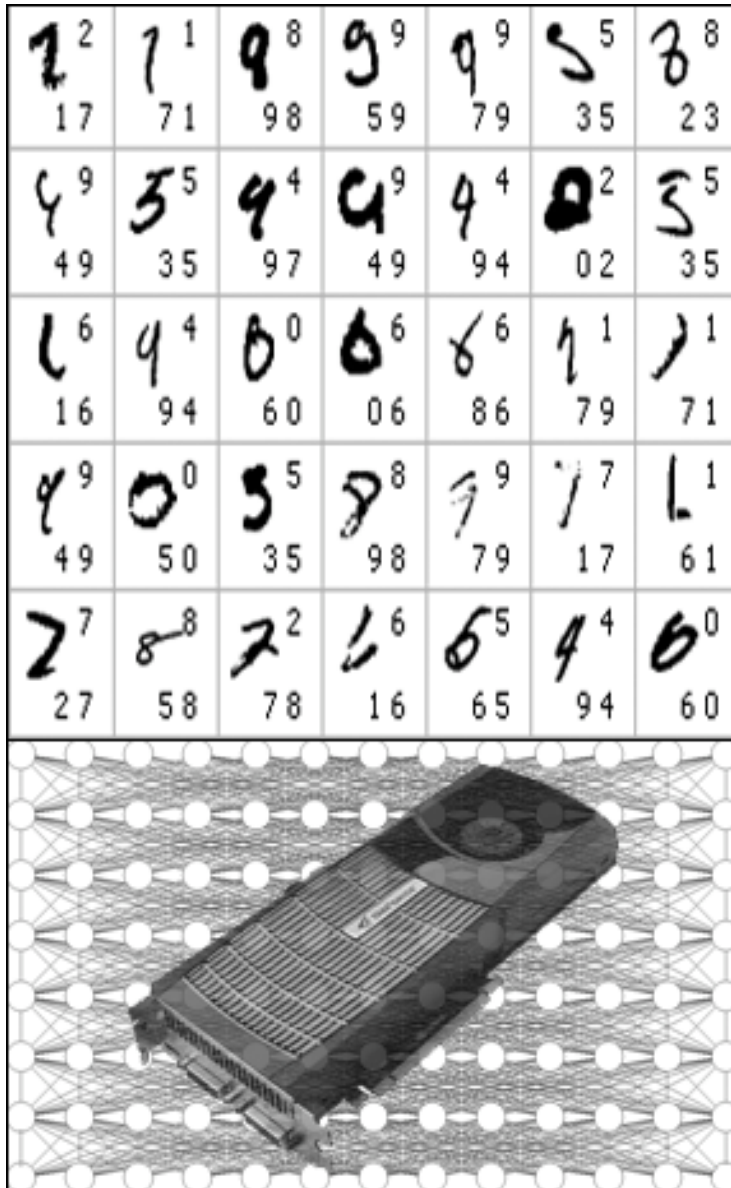
$$O^{ML}(S) = - \sum_{(\mathbf{x}, \mathbf{z}) \in S} \ln(p(\mathbf{z}|\mathbf{x}))$$

GRAVES, FERNANDEZ, GOMEZ, SCHMIDHUBER
 ICML 2006 - GRAVES, SCHMIDHUBER, NIPS 2010

GRAVES et al, ICASSP 2013: BEST
 RESULTS ON TIMIT SPEECH

2014 benchmark records with LSTM RNNs, often at major IT companies:

1. Large vocabulary speech recognition (Sak et al., [Google](#), Interspeech 2014)
2. English to French translation (Sutskever et al., [Google](#), NIPS 2014)
3. Text-to-speech synthesis (Fan et al., [Microsoft](#), Interspeech 2014)
4. Prosody contour prediction (Fernandez et al., [IBM](#), Interspeech 2014)
5. Language identification (Gonzalez-Dominguez et al., [Google](#), Intersp. 2014)
6. Medium vocabulary speech recognition (Geiger et al., Interspeech 2014)
7. Audio onset detection (Marchi et al., ICASSP 2014)
8. Social signal classification (Brueckner & Schuler, ICASSP 2014)
9. Arabic handwriting recognition (Bluche et al., DAS 2014)
10. Image caption generation (Vinyals et al., [Google](#), 2014)
11. Video to textual description (Donahue et al., 2014)

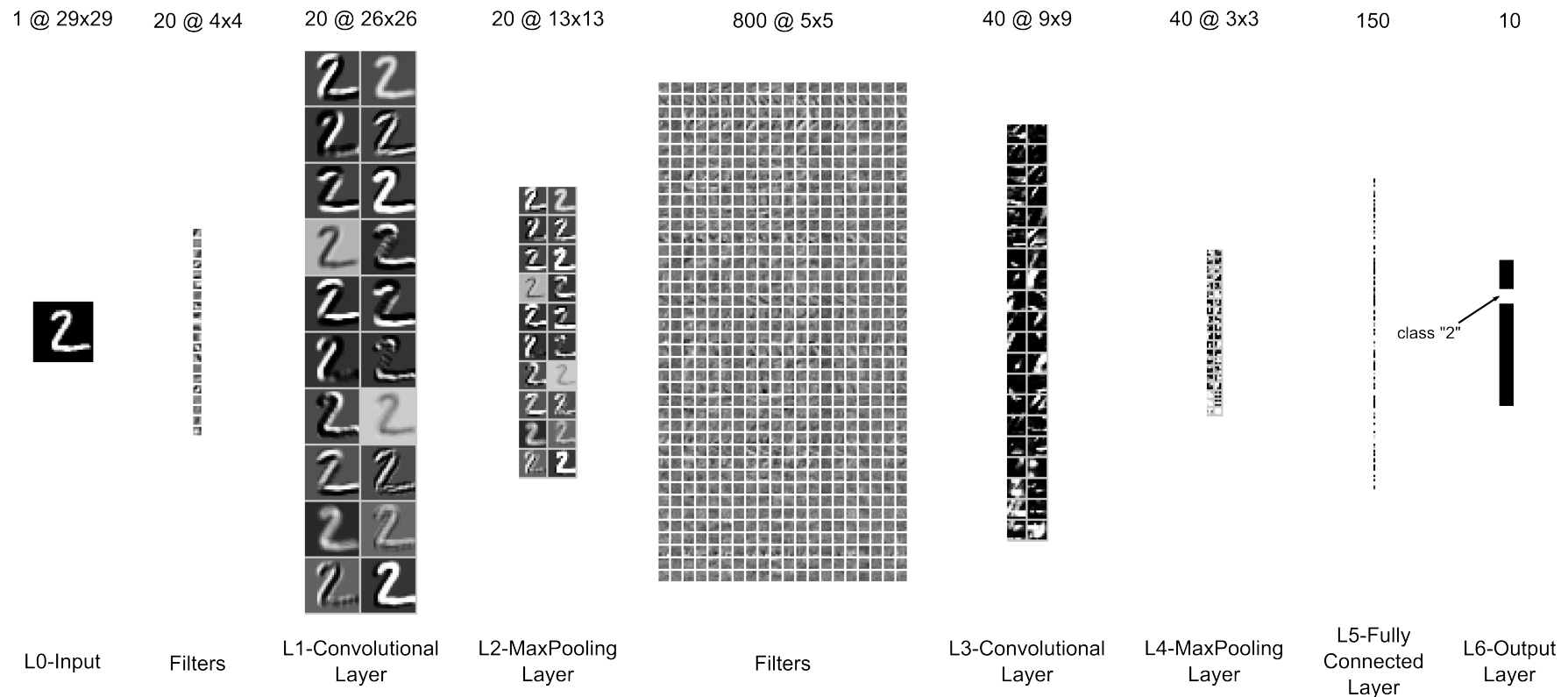


MNIST: 60000 DIGITS
 FOR TRAINING, 10000
 FOR TESTING,
 7 LAYER MLP; >12M
 WEIGHTS; TRAIN 200
 DAYS ON CPU = 5 ON
 GPU; >10¹⁵ WEIGHT
 UPDATES, 5B/s,
 2010: NEW WORLD
 RECORD 0.35%

TWO OLD IDEAS: BACKPROP (3-5 DECADES OLD),
 TRAINING PATTERN DEFORMATIONS (BAIRD 1990,
 2 DECADES OLD)

DEEP MAX-POOLING CNN ON GPU (IJCAI 2011)

ONE OUTPUT NEURON PER CLASS NORMALIZED BY SOFTMAX



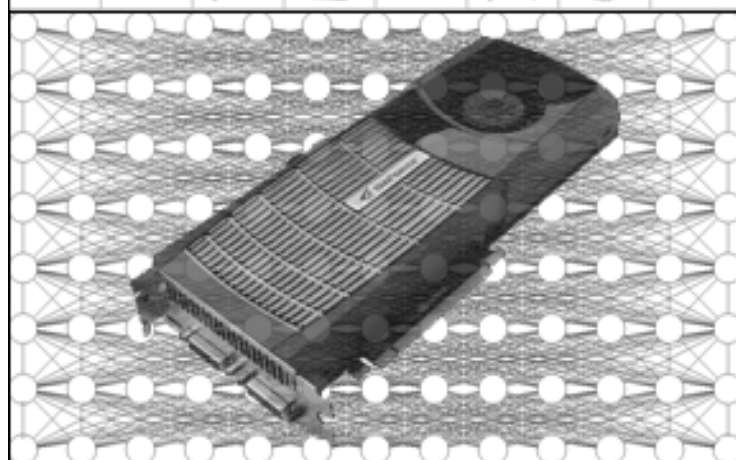
e.g., <http://www.idsia.ch/~juergen/deeplearning.html>

MPCNNs: 1979 1989
1992 2007 2010 2011



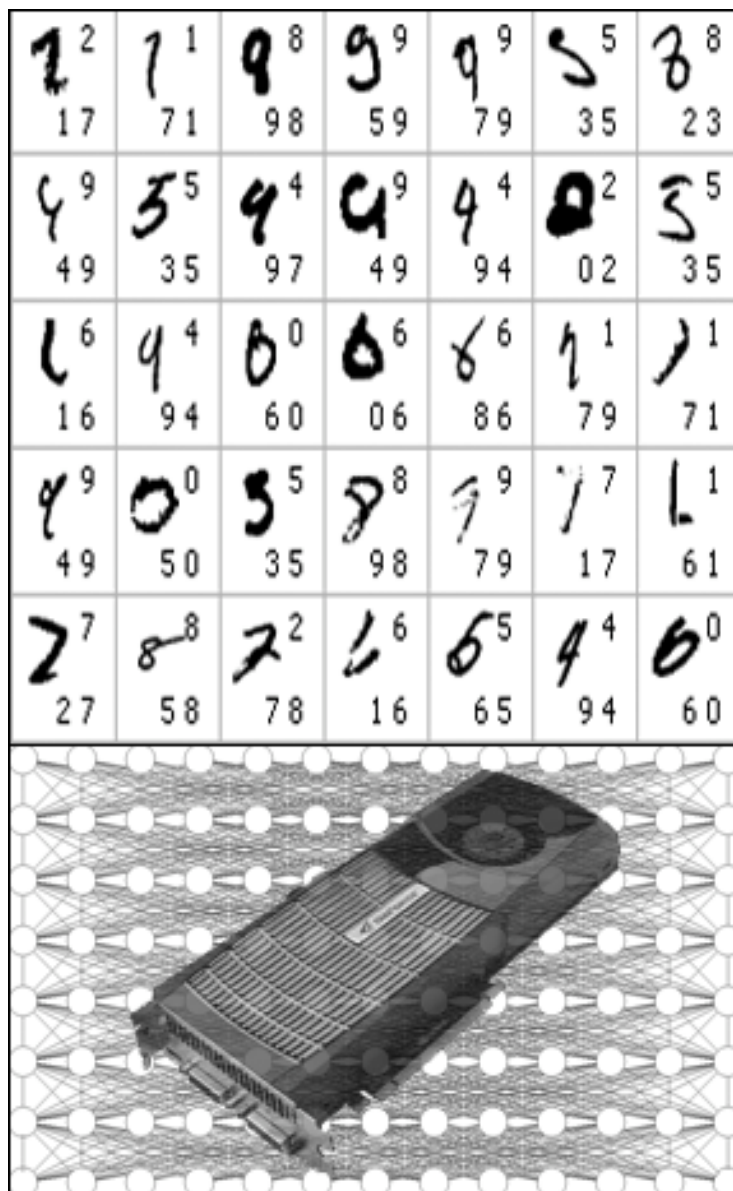
Alternating weight-replicating convolutional layers and subsampling layers: Fukushima 1979. BP for CNNs: LeCun et al 1989. Max-pooling (MP): Weng 1992 (like HMAX, Riesenhuber & Poggio 1999). BP for MPCNNs: Ranzato et al 2007, Scherer et al 2010 - GPUs - Ciresan et al (Swiss AI Lab IDSIA): winning feedforward contests since 2011

咱	攢	暫	贊	賍	脏	葬	遭
择	则	泽	贼	怎	增	憎	曾
诜	摘	壽	宅	窄	債	寨	瞻
湛	錠	樟	章	彰	漳	張	掌
照	罩	兆	肇	召	遮	折	哲
針	偵	枕	疼	診	震	振	鎮
郑	証	芝	枝	支	吱	蚰	知
止	趾	只	蚰	紙	志	摯	擲



ICDAR 2011
OFFLINE CHINESE
HANDWRITING
RECOGNITION
CONTEST (4000
CLASSES):

1ST & 2ND RANK
OCT 2013: AGAIN
BEST RESULTS,
**NEAR-HUMAN
PERFORMANCE**



DEEP SPARSE CNN

+ MAX-POOLING

+ MLP ON TOP: 1

YEAR ON CPU = 1

WEEK ON GPU; 5×10^9

WEIGHT UPDATES/s

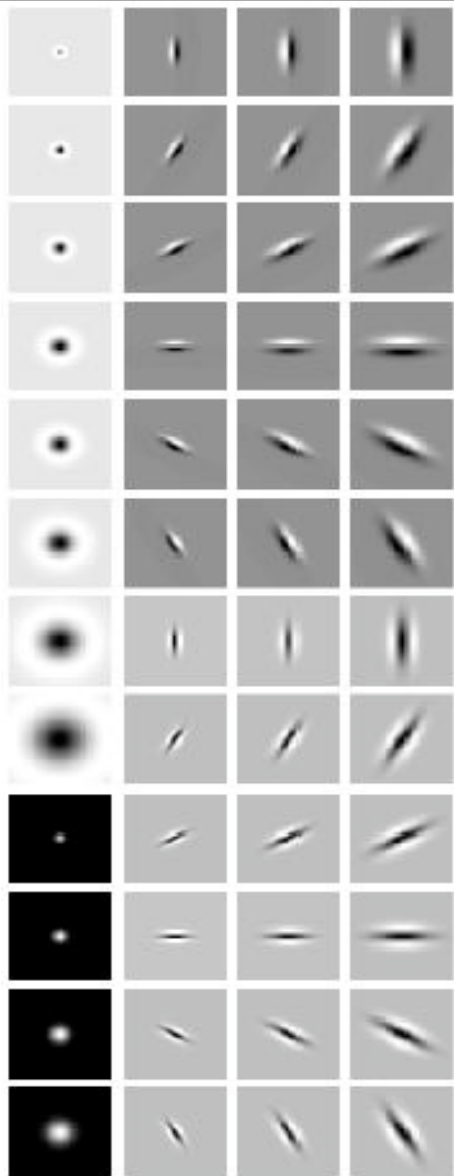
2011-2012: **FIRST**

HUMAN-COMPETITIVE

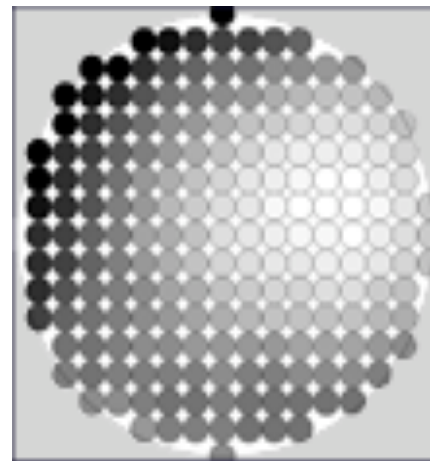
MNIST RESULT: 0.2%

(after almost a decade of
roughly 0.4%)

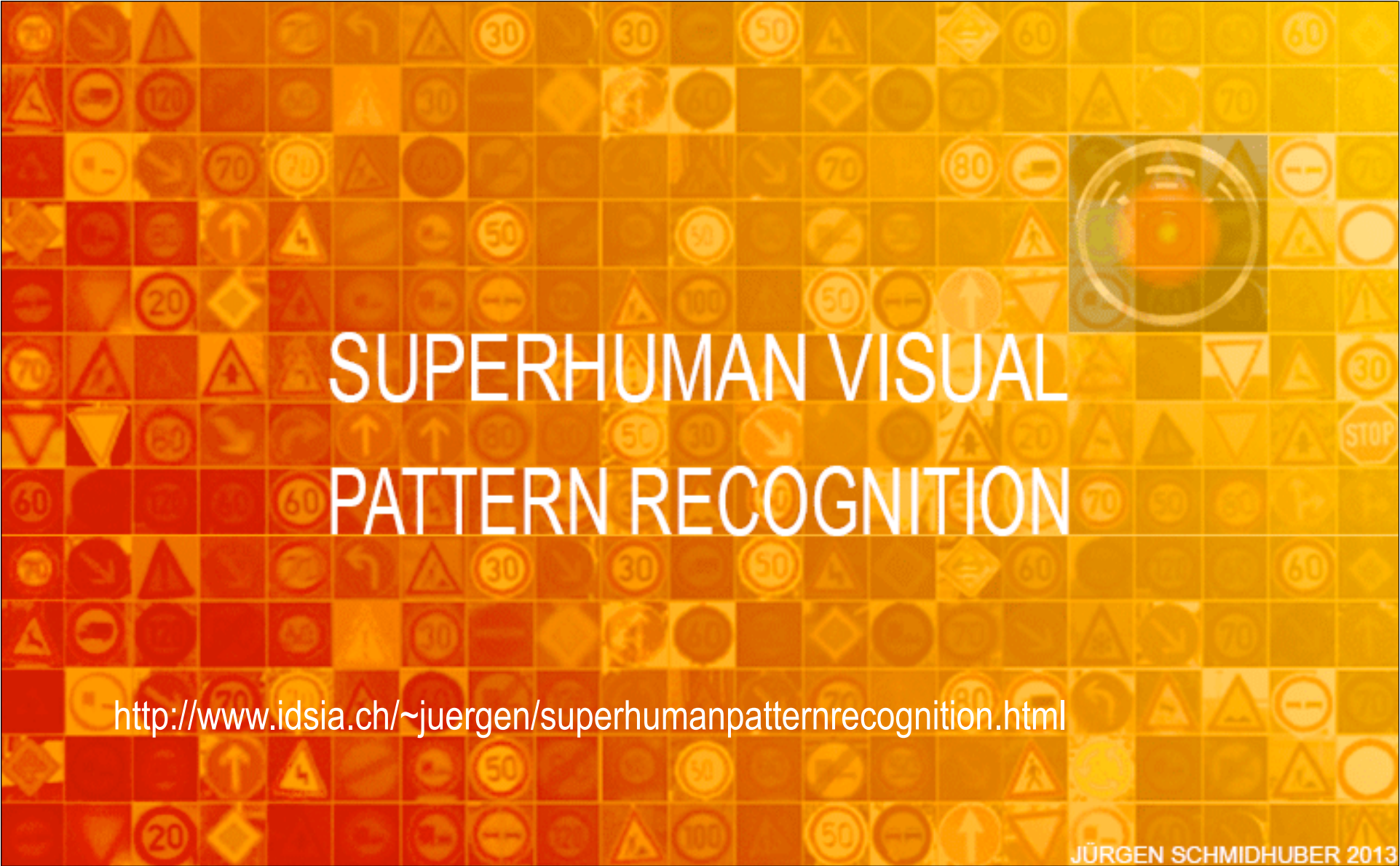
CIRESAN, MEIER, MASCI, GAMBARDELLA, SCHMIDHUBER
(IJCAI 2011) - CIRESAN, MEIER, SCHMIDHUBER (CVPR 2012)



PERIPHERY: FEATURE
DETECTORS VERY
SIMILAR TO THOSE OF
BIOLOGICAL BRAINS
OR THOSE FOUND BY
OUR UNSUPERVISED
METHODS (1992-)



IT'S ALL ABOUT COMPRESSION

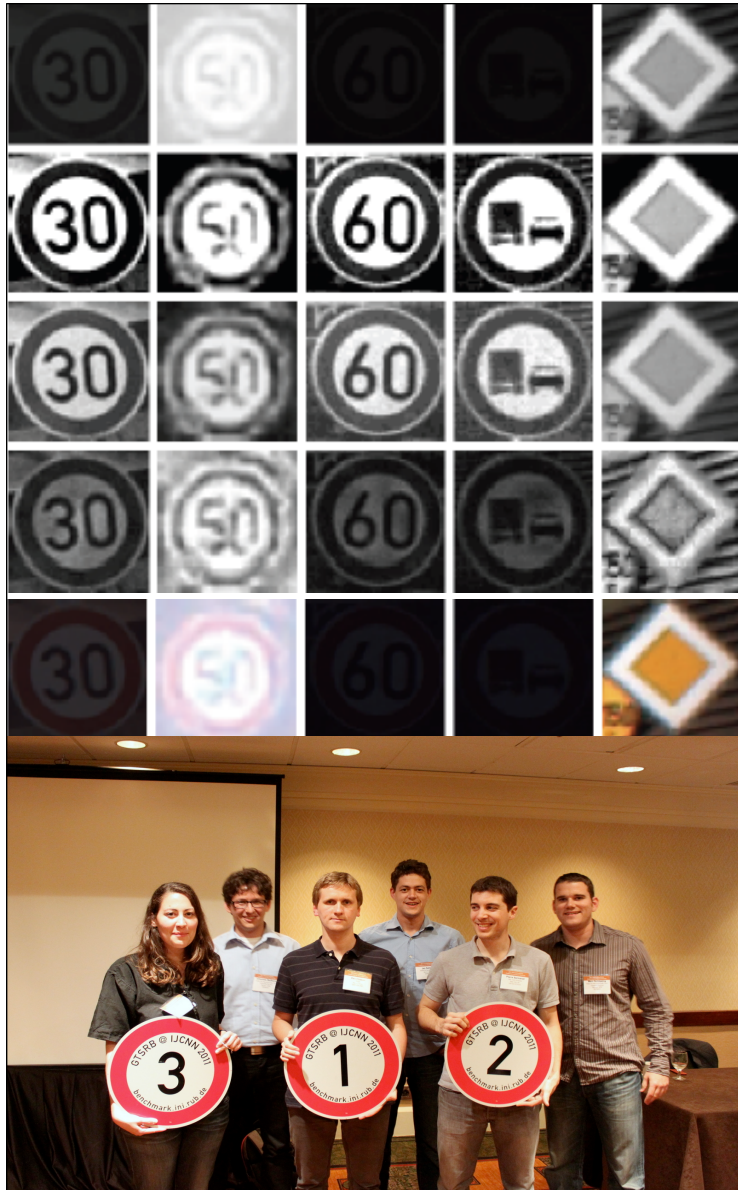


SUPERHUMAN VISUAL PATTERN RECOGNITION

<http://www.idsia.ch/~juergen/superhumanpatternrecognition.html>

JÜRGEN SCHMIDHUBER 2013

Traffic Sign Contest, Silicon Valley, 2011: twice better than humans
three times better than the closest artificial competitor
six times better than the best non-neural method



IJCNN 2011 ON-SITE
TRAFFIC SIGN
RECOGNITION
COMPETITION OF
2 AUGUST 2011:

1ST (0.56% ERROR)

2ND HUMANS (1.16%)

3RD (1.69%)

4TH (3.86%)

Ciresan, Meier, Masci,
Schmidhuber, Neural
Networks, 2012

ERNST DICKMANNNS
THE ROBOT CAR PIONEER
UNIBW MÜNCHEN, 1980s

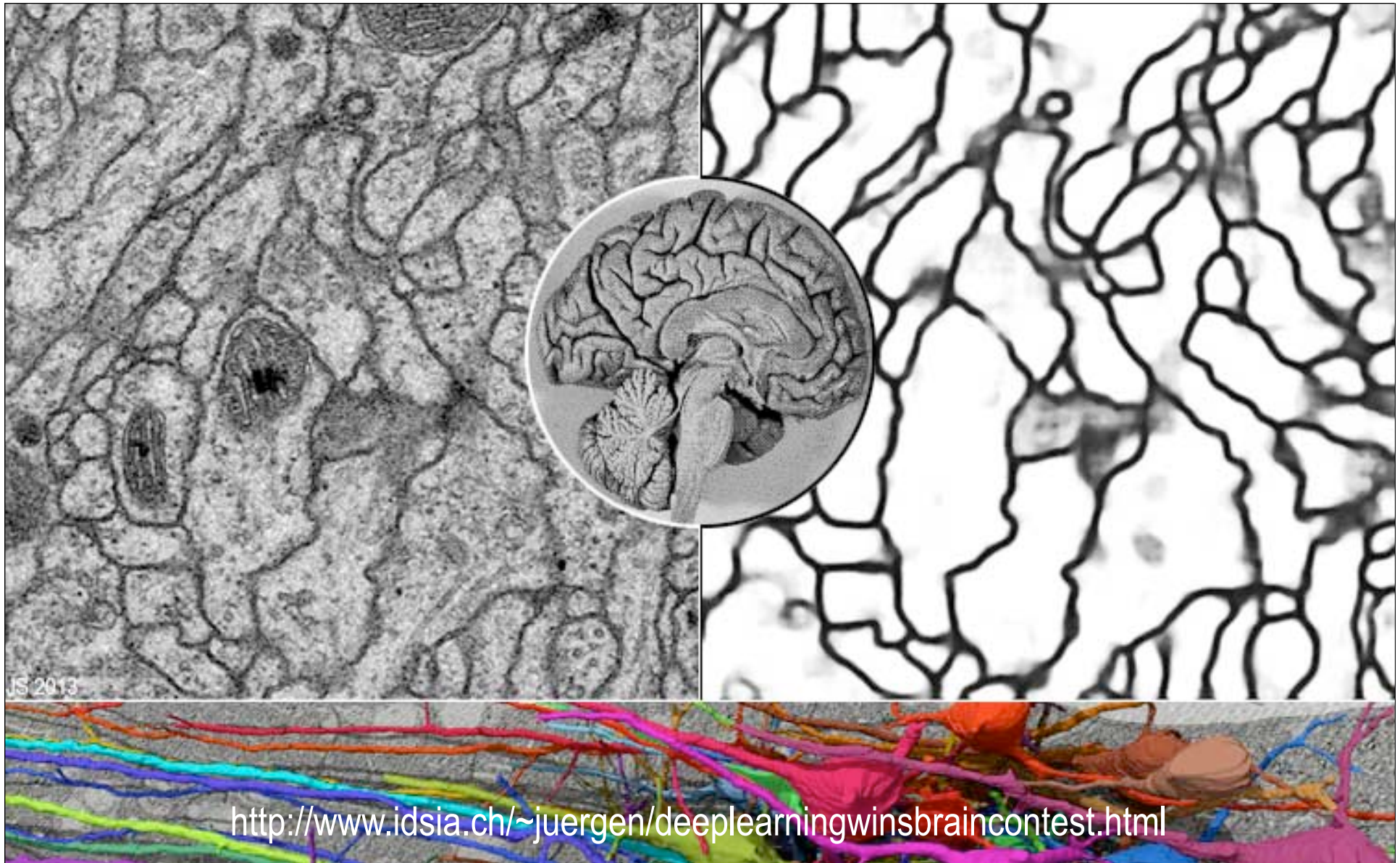


1995: MUNICH TO
DENMARK AND
BACK ON PUBLIC
AUTOBAHNS, UP TO
180 KM/H, NO GPS,
PASSING OTHER
CARS →

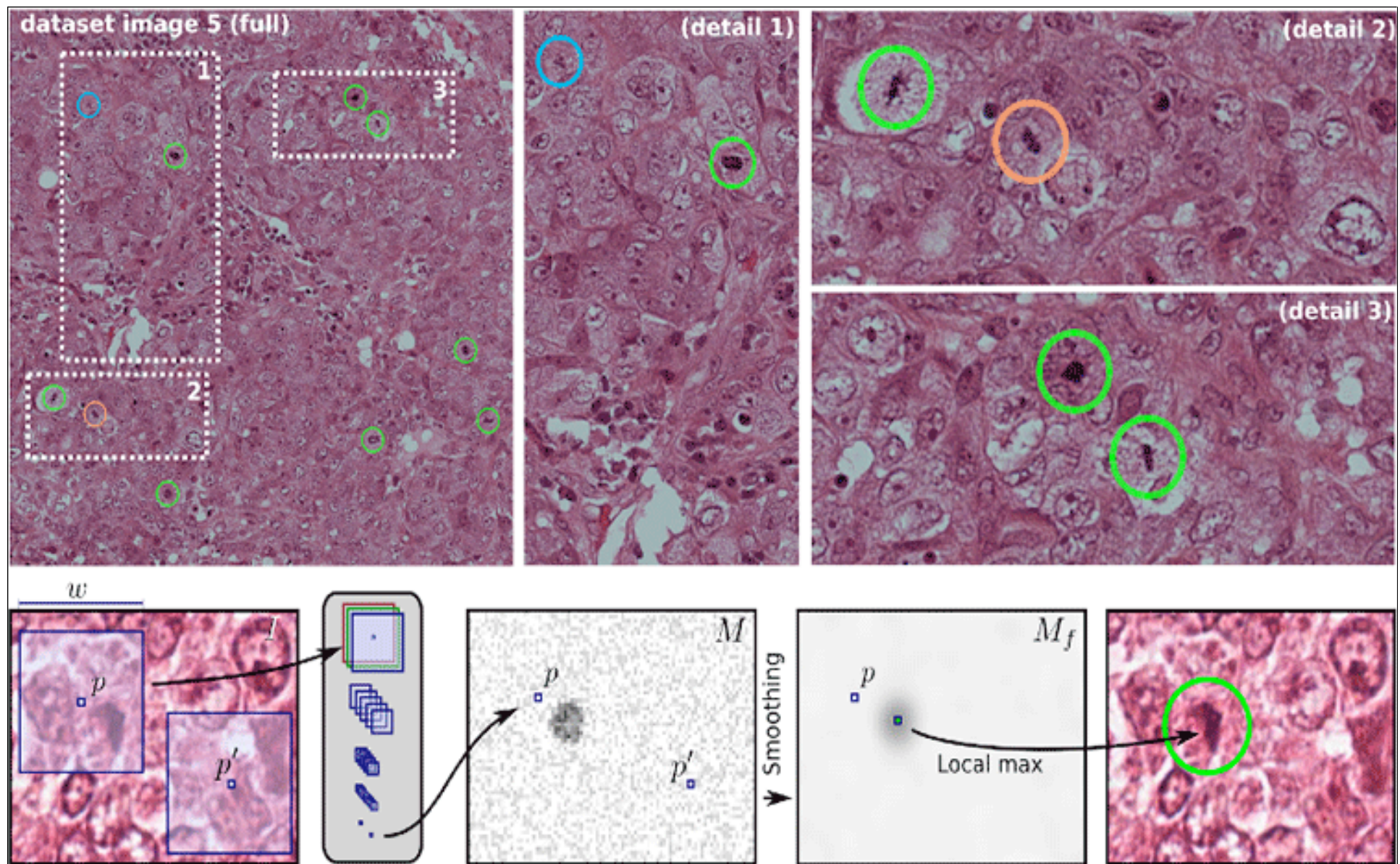


2014: 20 YEAR ANNIVERSARY OF SELF-DRIVING
CARS IN HIGHWAY TRAFFIC (DICKMANNNS, 1994)

<http://www.idsia.ch/~juergen/robotcars.html>



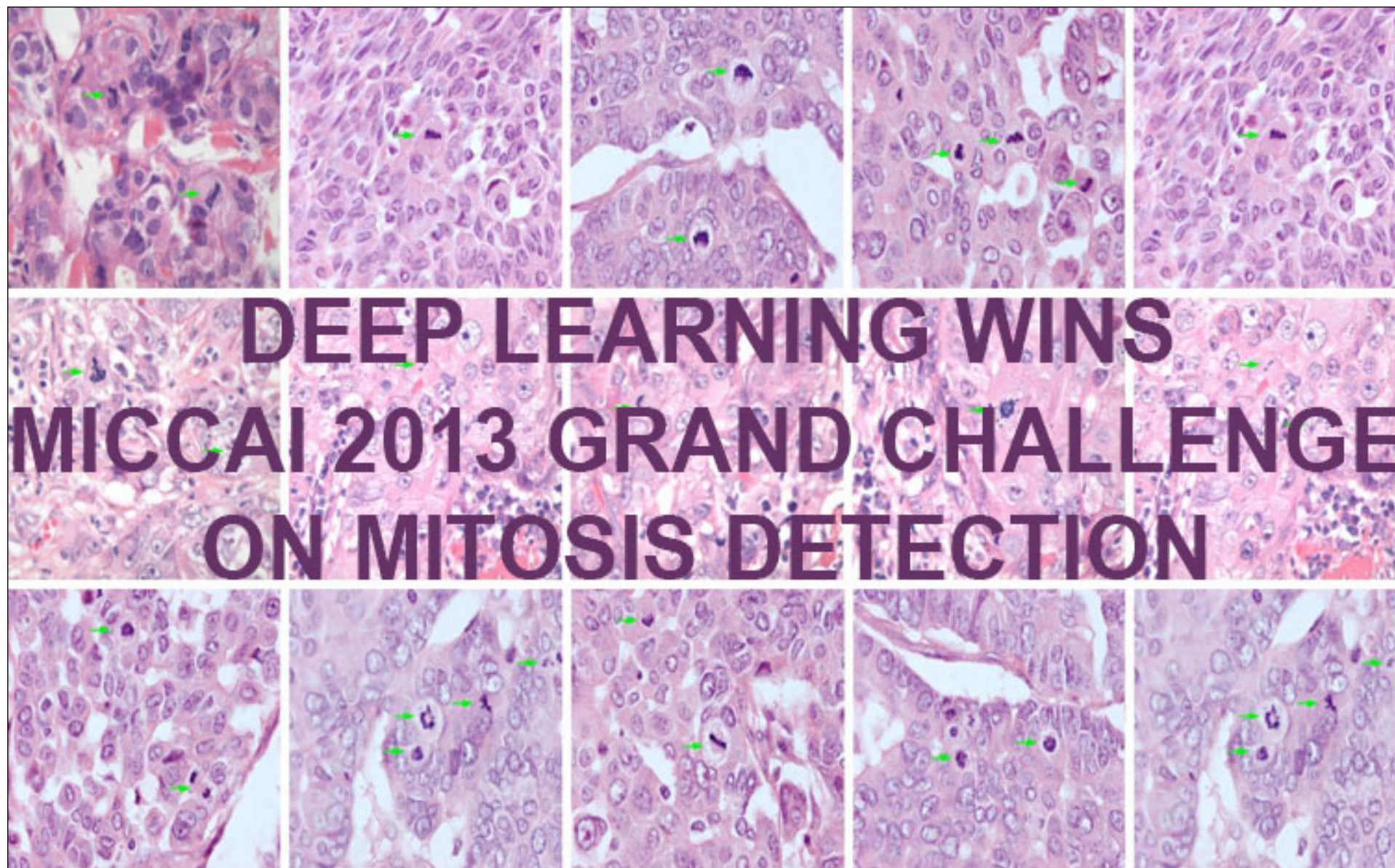
Deep Learning Wins ISBI 2012 Brain Image Segmentation Contest
First feedforward Deep Learner to win an **image segmentation** competition
(but compare deep recurrent LSTM 2009: segmentation & classification)



Deep Learning Wins ICPR 2012 Contest on Mitosis Detection

First pure Deep Learner to win a contest on **object detection** (in large images)

Very fast MPCNN scans: Masci, Giusti, Ciresan, Gambardella, Schmidhuber, ICIP 2013



<http://www.idsia.ch/~juergen/deeplearningwinsMICCAIgrandchallenge.html>

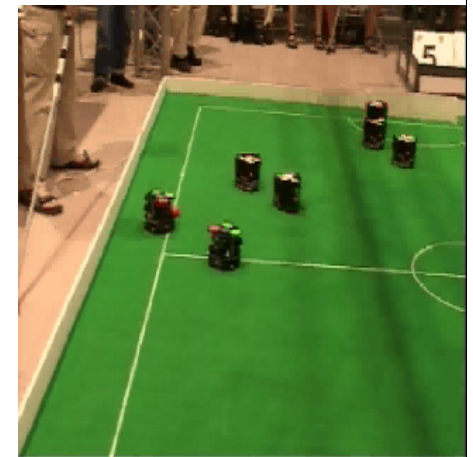
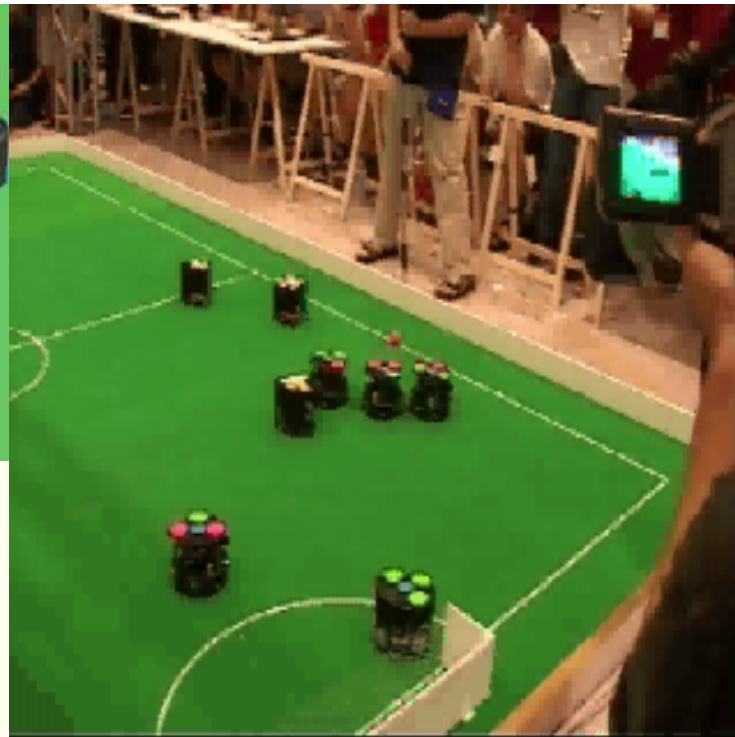
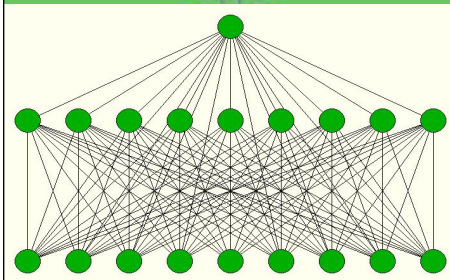
Thanks to Dan Ciresan & Alessandro Giusti

ROBOCUP WORLD CHAMPION 2004 FASTEST LEAGUE, UP TO 5M/S

LOOKAHEAD EXPECTATION & PLANNING WITH NEURAL
NETWORKS (J. SCHMIDHUBER, IEEE INNS 1990):
SUCCESSFULLY USED FOR ROBOCUP BY ALEXANDER
GLOYE-FÖRSTER (NOW IDSIA). MOVIE:

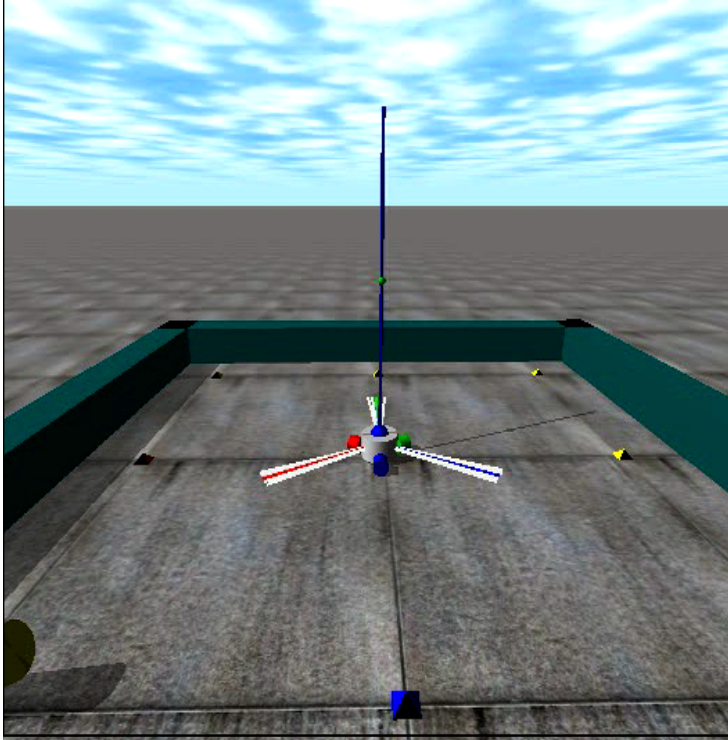
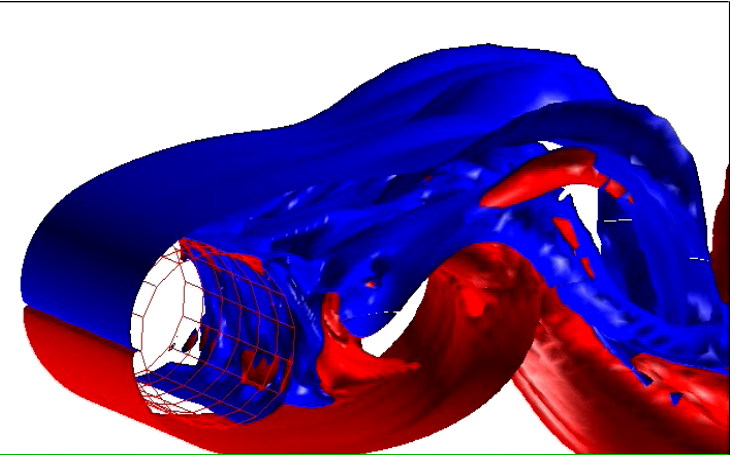
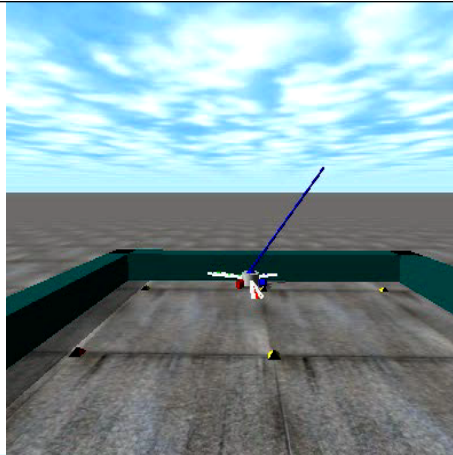


ALEX GLOYE-FÖRSTER,
IDSIA, LEADER OF THE
FU-FIGHTER ROBOCUP
TEAM OF FU BERLIN,
WORLD CHAMPION 2004

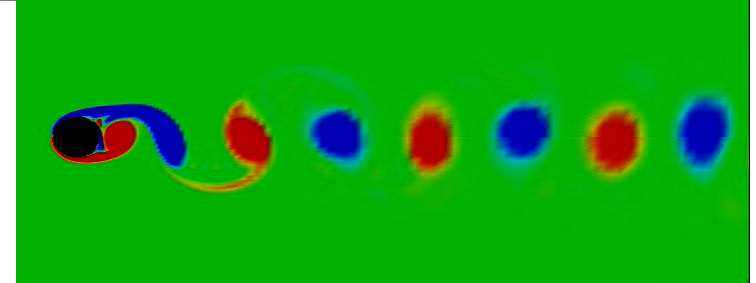


<http://www.idsia.ch/~juergen/learningrobots.html>

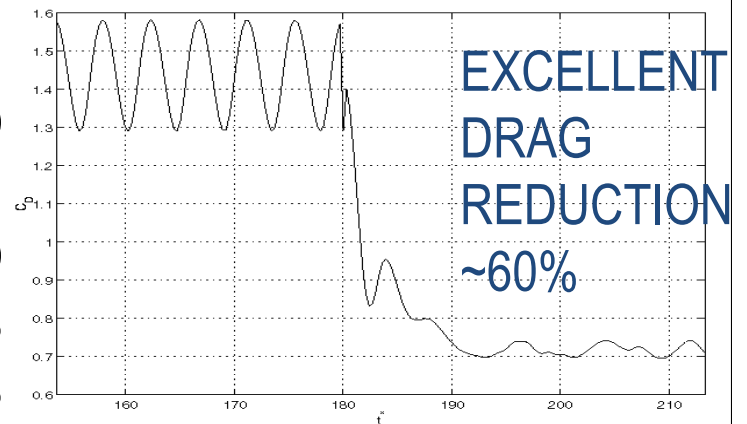
DIRECT POLICY SEARCH BY RNN EVOLUTION ETC



E.G., ROBOT
LEARNS TO
BALANCE 1 OR 2
POLES (3D JOINT)



WITH FAUSTINO
GOMEZ (IDSIA),
MICHELE MILANO
(ETHZ) & PETROS
KOUMOUTSAKOS



<http://www.idsia.ch/~juergen/evolution.html>



Finds Complex Neural Controllers with a Million Weights – RAW VIDEO INPUT!

Faustino Gomez, Jan Koutnik, Giuseppe Cuccu, J. Schmidhuber, GECCO 2013

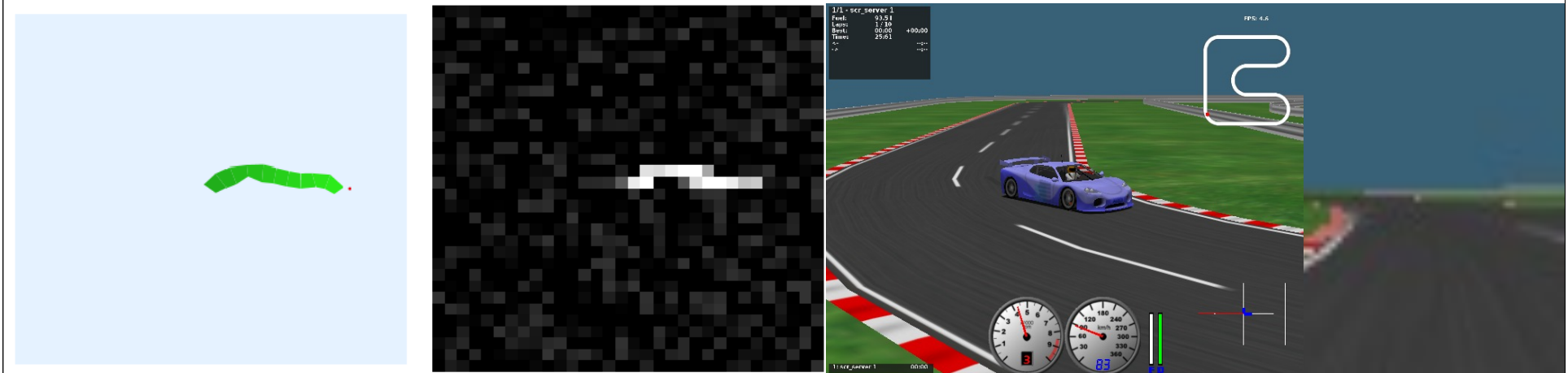


<http://www.idsia.ch/~juergen/compressednetworksearch.html>

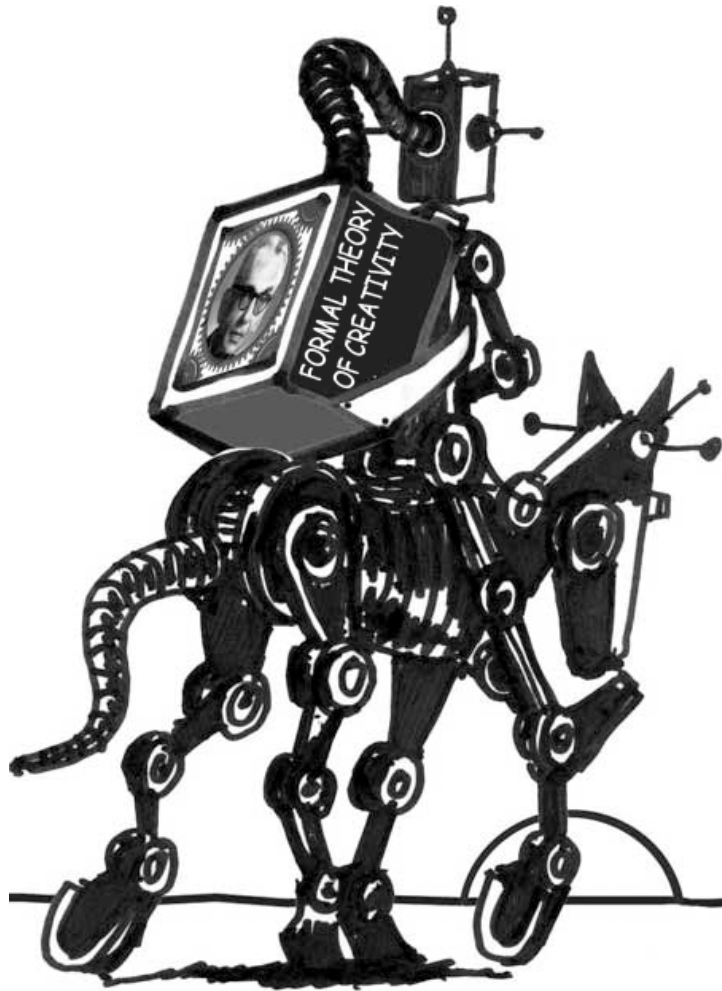
OCTOPUS-ARM CONTROL: 82 IN, 32 OUT, 3'680 W,
ONLY 20 DCT COEFFICIENTS, COMPRESSION 1:184

OCTOPUS-ARM WITH LOW-LEVEL VISION, 32X32 IN,
32 OUT, 33'824 W, 160 DCT, COMPRESSION 1:211

TORCS DRIVING, LOW-LEVEL VISION, 64X64 IN, 3
OUT, 1'115'139 W, 200 DCT, COMPRESSION 1:5575



<http://www.idsia.ch/~juergen/compressednetworksearch.html>



Maximize Future $\text{Fun}(\text{Data } X, O(t)) \sim \partial \text{CompResources}(X, O(t)) / \partial t$

FORMAL THEORY OF FUN & NOVELTY & SURPRISE & ATTENTION & CREATIVITY & CURIOSITY & ART & SCIENCE & HUMOR

schmid

<http://www.idsia.ch/~juergen/creativity.html>

E.g., Conn. Sci. 18(2):173-187, 2006; IEEE TAMd, 2(3):230-247, 2010